# flow of control, negation, cut, $2^{\text {nd }}$ order programming, tail recursion 

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## simplicity hides complexity

simple and/or composition of goals hides complex control patterns not easily represented by traditional flowcharts

- may not be a bad thing
$\square$ want important aspects of logic and algorithm to be clearly represented and irrelevant details to be left out


## procedural and declarative semantics

Prolog programs have both a declarative/logical semantics and a procedural semantics
declarative semantics: query holds if it is a logical consequence of the program
$\square$ procedural semantics: query succeeds if a matching fact or rule succeeds, etc.

- defines order in which goals are attempted, what happens when they fail, etc.


## and \& or

Prolog' s and (, ) \& or (; and alternative facts and rules that match a goal) are not purely logical operations
often important to consider the order in which goals are attempted

- left to right for "," and ";"
- top to bottom for alternative facts/rules


## and is not always commutative, e.g.

```
    sublistV1(S, L):- append(_, L1, L),
    append(S, _, L1).
```

i.e. $S$ is a sublist of $L$ if $L 1$ is any suffix of $L$ and $S$ is a prefix of $L 1$

- sublistV2(S, L):- append(S, _, L1), append (_, L1 ,L).
i.e. $S$ is a sublist of $L$ if $S$ is a prefix of some list $L 1$ and $L 1$ is any suffix of $L$


## and is not always commutative, e.g.

- ?- sublistV1([c,b], [a, b, c, d]). false.
sublistV2([c,b], [a, b, c, d]). ERROR: Out of global stack why?


## uses of or (;)

$\square$ or ";" can be used to regroup several rules with the same head
e.g.
parent( $X, Y$ ):- mother $(X, Y)$; father $(X, Y)$.
$\square$ can improve efficiency by avoiding redoing unification
■";" has lower precedence than ","

## Prolog negation

$\square$ Prolog uses " $\backslash+$ ", "not provable" or negation as failure different from logical negation
?- \+ goal. succeeds if ?- goal. fails interpreting $\backslash+$ as negation amounts to making the closed-world assumption

## example

$\square$ Given program:
human(ulysses). human(penelope).
mortal(X):- human(X).
$\square$ ?- \+ human(jason).
Yes
$\square$ In logic, the axioms corresponding to the program don't entail ᄀHuman(Jason).

## semantics of free variables in \+ is "funny"

$\square$ normally, variables in a query are existentially quantified from outside e.g. ?- $p(X), q(X)$. represents "there exists $x$ such that $\mathrm{P}(x) \& \mathrm{Q}(x)$ "
$\square$ but ?- $\backslash+(p(X), q(X))$. represents "it is not the case that there exists $x$ such that $\mathrm{P}(x) \& \mathrm{Q}(x)$ "

## To avoid this problem

$\square$ \+ works correctly if its argument is instantiated
so for example in
intersect([X|L], Y, I):-
\+ member( $\mathrm{X}, \mathrm{Y}$ ), intersect( $\mathrm{L}, \mathrm{Y}, \mathrm{I}$ ).
$X$ and $Y$ should be instantiated

## example

$\square$ Given program:
animal(cat). vegetable(turnip).
$\square$ ?- \+ animal(X), vegetable(X).
No why?
$\square$ ?- vegetable( $X$ ), \+ animal( $X$ ).
$X=$ turnip why?

## guarding the "else"

can't rely on implicit negation in predicates that can be redone
$\square$ in predicates with alternative rules, each rule should be logically valid (if backtracking can occur)
safest thing is repeating the condition with negation

## e.g. intersect

```
intersect([], _, []).
intersect([X|L], Y, [X|I]):-
    member(X,Y), intersect(L, Y, I).
intersect([X|L], Y, I):-
    \+ member(X,Y), intersect(L, Y, I).
is OK.
```


## e.g. intersect

- intersect([], _, []).
intersect([X|L], Y, [X|I]):-
member( $\mathrm{X}, \mathrm{Y})$, intersect( $\mathrm{L}, \mathrm{Y}, \mathrm{I})$.
intersect([_|L], Y, I):-intersect(L, Y, I).
is buggy.
?- intersect([a], [b, a], []). succeeds. why?


## inhibiting backtracking

$\square$ the cut operator "!" is used to control backtracking
If the goal G unifies with H in program
H :- ....
$H:-G_{1}, \ldots, G_{i},!, G_{j}, \ldots, G_{k}$.
H:-...
and gets past the !, and $G_{j}, \ldots, G_{k}$ fails, then the parent goal G immediately fails. $\mathrm{G}_{1}, \ldots, \mathrm{G}_{\mathrm{i}}$ won't be retried and the subsequent matching rules won't be attempted.

## Using! e.g. intersect

cut can be used to improve efficiency, e.g.
intersect([], _, []).
intersect([X|L], Y, [X|I]):-
member( $\mathrm{X}, \mathrm{Y})$, intersect $(\mathrm{L}, \mathrm{Y}, \mathrm{I})$. intersect(([X|L], Y, I):-
$\+$ member $(X, Y)$, intersect( $L, Y, I)$. retests member( $\mathrm{X}, \mathrm{Y}$ ) twice

## e.g. intersect

using cut, we can avoid this
intersect([], _, []).
intersect([X|L], Y, [X|I]):-
member(X,Y), !, intersect( $L, Y, I)$.
intersect([_|L], Y, I):-intersect(L, Y, I).
$\square$ means that the last 2 rules are a conditional branch

## cut can be used to define useful features

If goal $G$ should be false when $C_{1}, \ldots, C_{n}$ holds, can write
G :- $C_{1}, \ldots, C_{n}$ !, fail.
$\square$ not provable can be defined using cut \+ G :- G, !, fail.
$1+G$.

## control predicates

$\square$ true (really success), e.g.
G :- Cond1; Cond2; true.
$\square$ fail (opposite of true)
$\square$ repeat (always succeeds, infinite number of choice points)
loopUntilNoMore:- repeat, doStuff, checkNoMore.
but tail recursion is cleaner, e.g. loop :- doStuff, (checkNoMore; loop).

## forcing all solutions

test :- member(X, [1, 2, 3]), nl, print(X),
fail.
\% no alternative sols for print( X ) and nl
\% but member has alternative sols
?- test.
1
2
3
No

## 2nd order features: bagof \& setof

- ?- bagof(T,G,L). instantiates $L$ to the list of all instances of $T$ such for which $G$ succeeds, e.g.
?- $\operatorname{bagof(X,(member(X,[2,5,7,3,5]),X>=3),L).~}$
X = _G172
$\mathrm{L}=[5,7,3,5]$
Yes


## 2nd order features: bagof \& setof

```
setof is similar to bagof except that it removes
duplicates from the list, e.g.
?- setof(X,(member(X,[2,5,7,3,5]),X >= 3),L).
X = _G172
L = [3, 5, 7]
Yes
can collect values of several variables, e.g.
?- bagof(pair(X,Y),(member(X,[a,b]),member(Y,[c,d])),
    L).
X = _G157
Y = _G158
L = [pair(a,c), pair(a,d), pair(b,c), pair(b,d)]
Yes
```


## 2nd order features

setof and bagof are called 2nd order features because they are queries about the value of a set or relation
in logic, this is quantification over a set or relation
$\square$ not allowed in first order logic, but can be done in $2 n d$ order logic

## entering and leaving

Trace steps are labelled:
Call: enter the procedure
Exit: exit successfully with bindings for variable
Fail: exit unsuccessfully
Redo: look for an alternative solution
4 ports model

## e.g. factorial

simple implementation:
fact $(0,1)$.
fact( $N, F):-N>0, N 1$ is $N-1$,
fact( $\mathrm{N} 1, \mathrm{~F} 1$ ), F is $\mathrm{N} * \mathrm{~F} 1$.
$\square$ close to mathematical definition
$\square$ but not tail-recursive
requires $\mathrm{O}(\mathrm{N})$ in stack space

## e.g. factorial

better implementation:
fact(N,F):- fact1(N,1,F).
fact1(0,F,F).
fact1(N,T,F):- N > 0, T1 is T * N,
N1 is $\mathrm{N}-1$, fact1(N1,T1,F).
$\square$ uses accumulator
$\square$ is tail-recursive and each call can
replace the previous call
can prove correctness

## Tail recursion optimization in Prolog

suppose have goal $A$ and rule $A$ : :- $B_{1}$, $B_{2}, \ldots, B_{n-1}, B_{n}$. and $A$ unifies with $A^{\prime}$ and $B_{2}, \ldots, B_{n-1}$ succeed
if there are no alternatives left for $A$ and for $B_{2}, \ldots, B_{n-1}$ then can simply replace $A$ by $B_{n}$ on execution stack in such cases the predicate $A$ is tail recursive
nothing left to do in $A$ when $B_{n}$ succeeds or fails/backtracks, so we can replace
call stack frame for $A$ by $B_{n}$ 's; recursion can be as space efficient as iteration

## e.g. append

$\square$ append([],L,L).
append([X|R],L,[X|RL]):append( $R, L, R L$ ).
$\square$ append is tail recursive if first argument is fully instantiated
$\square$ Prolog must detect the fact that there are no alternatives left; may depend on clause indexing mechanism used
$\square$ use of unification means more relations are tail recursive in Prolog than in other languages

## split

split([],[],[]).
split([X],[X],[]).
split([X1,X2|R],[X1|R1],[X2|R2]):split(R,R1,R2).

## Tail recursive!

## merge

```
merge([],L,L).
merge(L,[],L).
merge([X1|R1],[X2|R2],[X1|R]):-
    order(X1,X2), merge(R1,[X2|R2],R).
merge([X1|R1],[X2|R2],[X2|R]):-
    not order(X1,X2), merge([X1|R1],R2,R).
```

Tail recursive, but lack of alternatives may be hard to detect (can use cut to simplify).

## merge sort

mergesort([],[]).
mergesort([X],[X]).
mergesort(L,S):- split(L,L1,L2),
mergesort(L1,S1),
mergesort(L2,S2), merge(S1,S2,S).

## for more on tail recursion

see Sterling \& Shapiro The Art of Prolog Sec. 11.2

