

# ENG2200

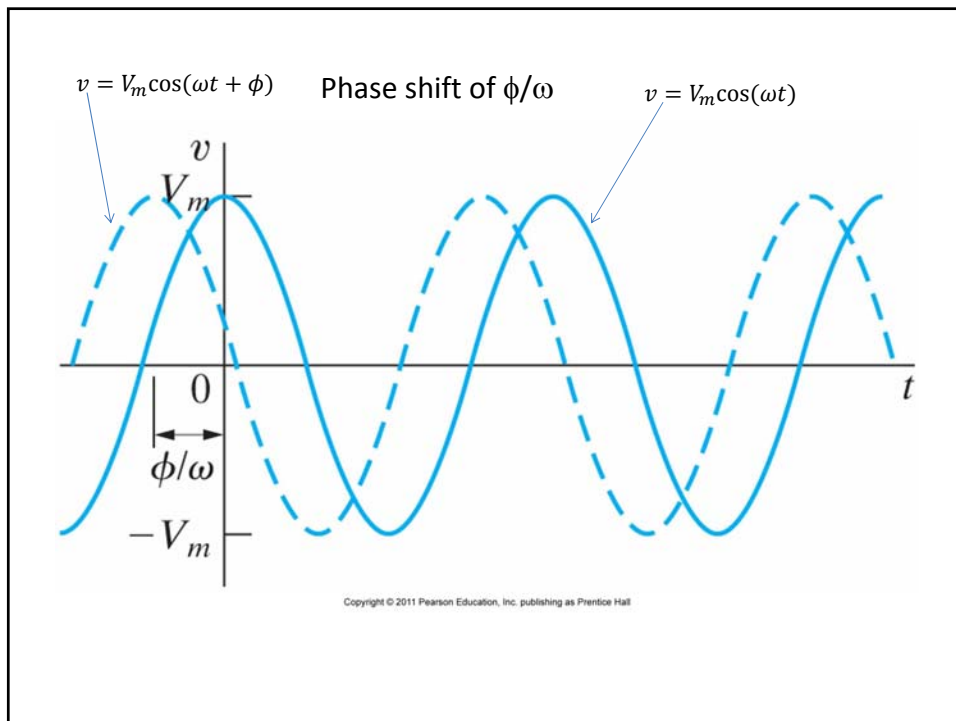
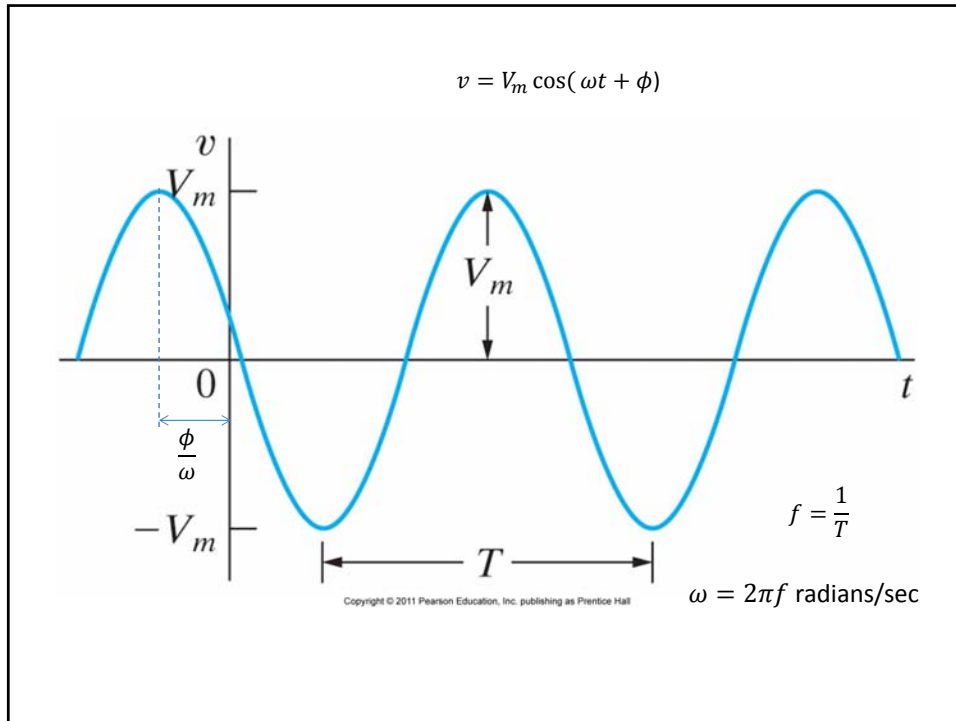
## Electric Circuits

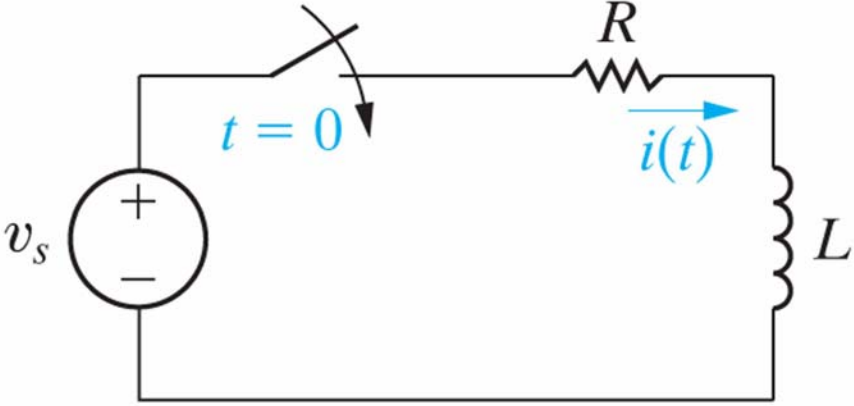
### Chapter 9

#### Sinusoidal Steady State Analysis

### Objectives

- Understanding phasor concept and be able to perform phasor transform and inverse phasor transform.
- Be able to transform a circuit with sinusoidal source into the frequency domain using phasor transform
- Know how to use circuits analysis techniques to solve circuits in the frequency domain.
- Be able to use phasor in analyzing circuits with ideal transformers.





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$$L \frac{di}{dt} + iR = V_m \cos(\omega t + \phi)$$

$$i = \frac{-V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos(\phi - \theta) e^{-(R/L)t} + \frac{V_m}{\sqrt{R^2 + \omega^2 L^2}} \cos(\omega t + \phi - \theta)$$

## RMS value

$$V_{rms} = \sqrt{\frac{1}{T} \int_{t_0}^{t_0+T} V_m^2 \cos^2(\omega t + \phi) dt}$$

$$V_{rms} = \frac{V_m}{\sqrt{2}}$$

Why RMS?

## The Phasor

- The phasor is a complex number that carries the amplitude and phase angle information of a sinusoidal function.
- Euler's identity  $e^{\pm j\theta} = \cos \theta \pm j \sin \theta$

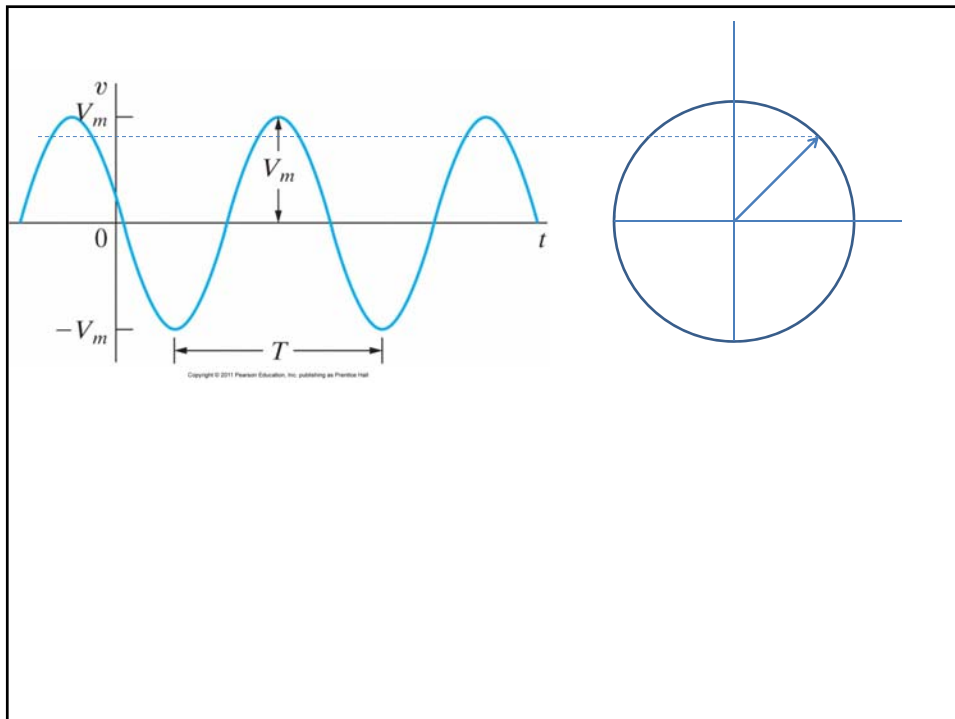
$$\cos \theta = \Re\{e^{j\theta}\}$$

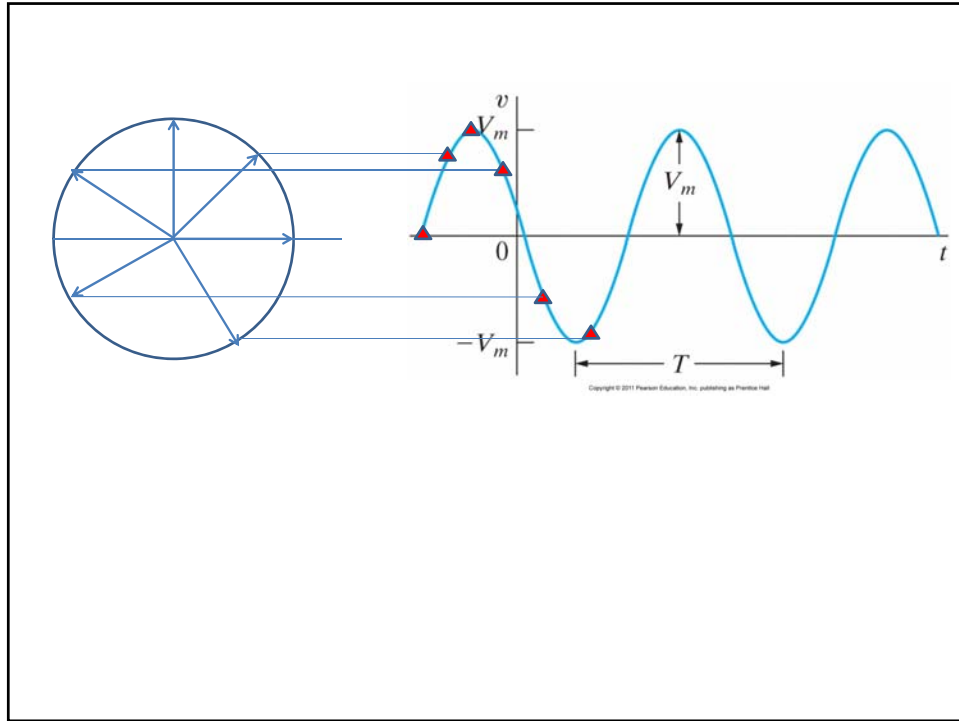
$$\sin \theta = \Im\{e^{j\theta}\}$$

$$v = V_m \cos(\omega t + \phi)$$

$$v = \Re\{V_m e^{j\phi} e^{j\omega t}\}$$

$$Ae^{j\phi} = A \angle \phi^\circ$$





## The inductor

$$v = L \frac{di}{dt}$$

$$v = V_m \cos(\omega t)$$

$$di = \frac{1}{L} V_m \cos(\omega t) dt$$

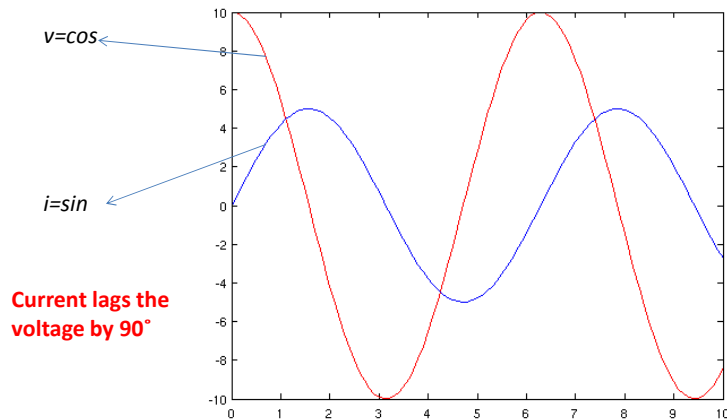
$$i = \frac{1}{L} V_m \int \cos(\omega t) dt$$

$$i = \frac{V_m}{\omega L} \sin(\omega t) = \frac{V_m}{\omega L} \cos(\omega t - \frac{\pi}{2})$$

$$I = \frac{V_m}{\omega L} e^{-j\pi/2} = \frac{V_m}{\omega L} \angle -\pi/2$$

$$Z = \frac{v}{i} = \omega L \angle \pi/2 = \textcircled{j\omega L}$$

A plot showing the phase relationship between the current and voltage at the terminals of an inductor



## The Capacitor

$$i = C \frac{dv}{dt}$$

$$v = V_m \cos(\omega t)$$

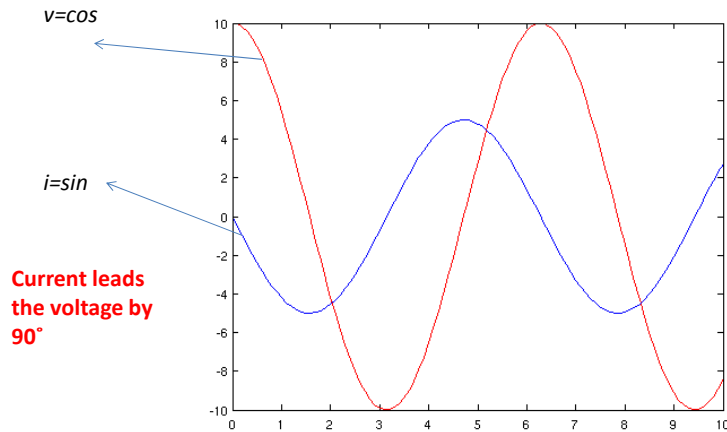
$$i = CV_m \frac{d}{dt} \cos(\omega t)$$

$$i = -C\omega V_m \sin(\omega t) = \omega CV_m \cos(\omega t + \frac{\pi}{2})$$

$$I = \omega CV_m e^{j\pi/2} = \omega CV_m \angle \pi/2$$

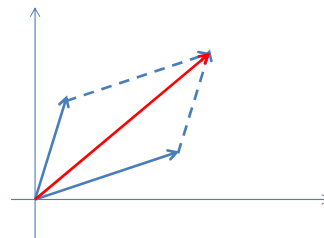
$$Z = \frac{v}{i} = \frac{1}{\omega C} \angle -\pi/2 = \frac{-j}{\omega C} = \frac{1}{j\omega C}$$

A plot showing the phase relationship between the current and voltage at the terminals of a capacitor



## Adding Complex Numbers

$$\pm \begin{array}{l} x_1 + jy_1 \\ x_2 + jy_2 \\ \hline (x_1 + x_2) \pm j(y_1 + y_2) \end{array}$$

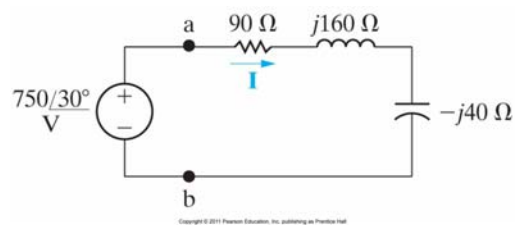
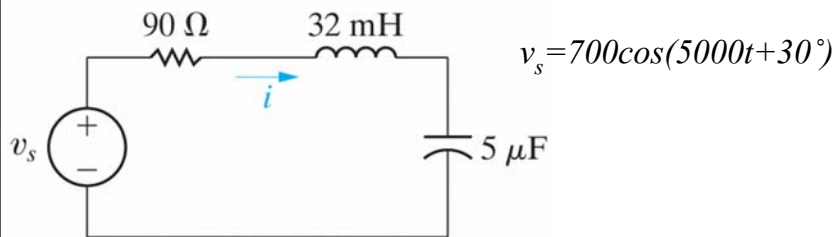


## Multiplication

$$\begin{array}{r} \times \quad \begin{array}{l} x_1 + jy_1 \\ x_2 + jy_2 \\ \hline \end{array} \\ (x_1 x_2 - y_1 y_2) + j(x_1 y_2 + x_2 y_1) \end{array}$$

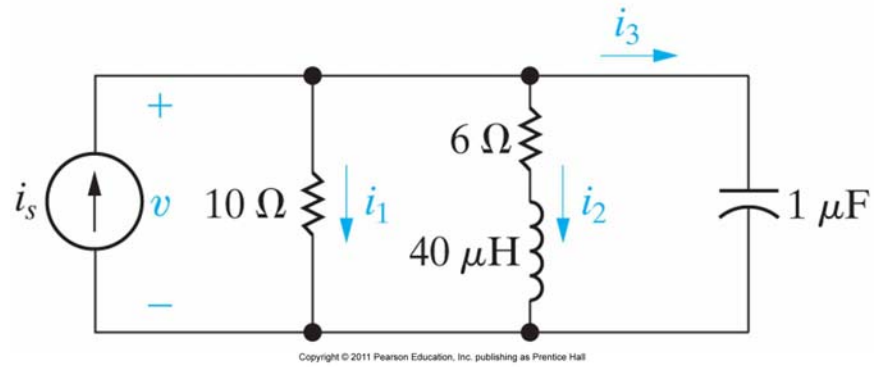
$$A_1 \angle \theta_1 \times A_2 \angle \theta_2 = A_1 A_2 \angle \theta_1 + \theta_2$$

## Example



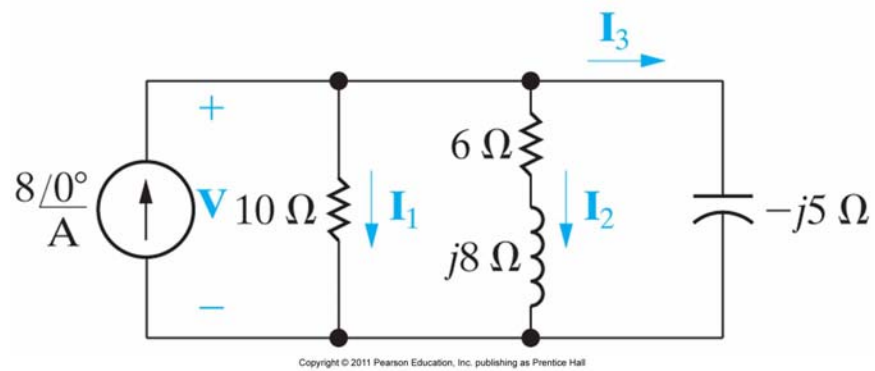


### Example

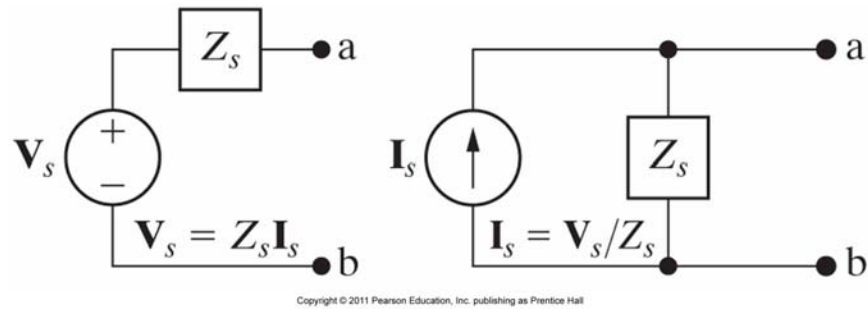


$$i_s = 8 \cos 200,000t$$

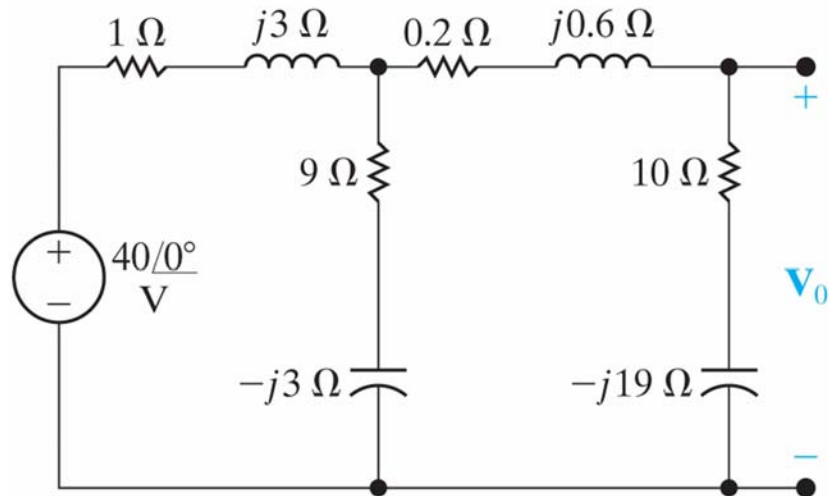
### Example



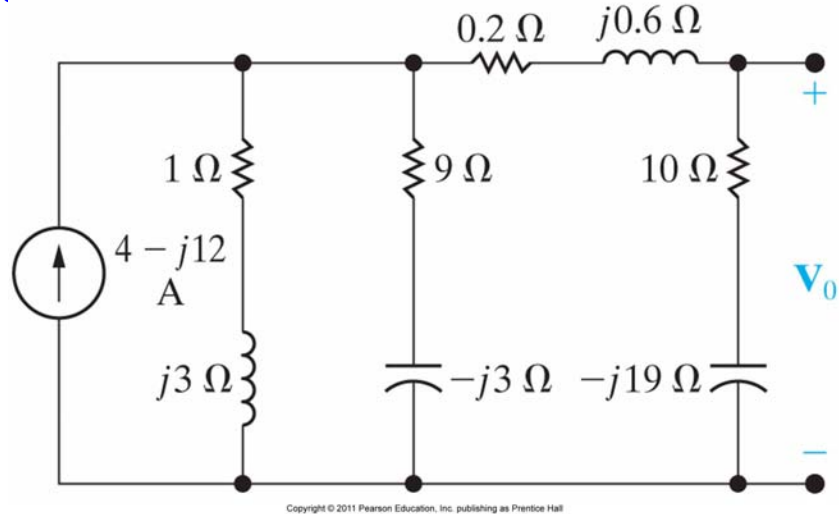
**Figure 9.24** A source transformation in the frequency domain.



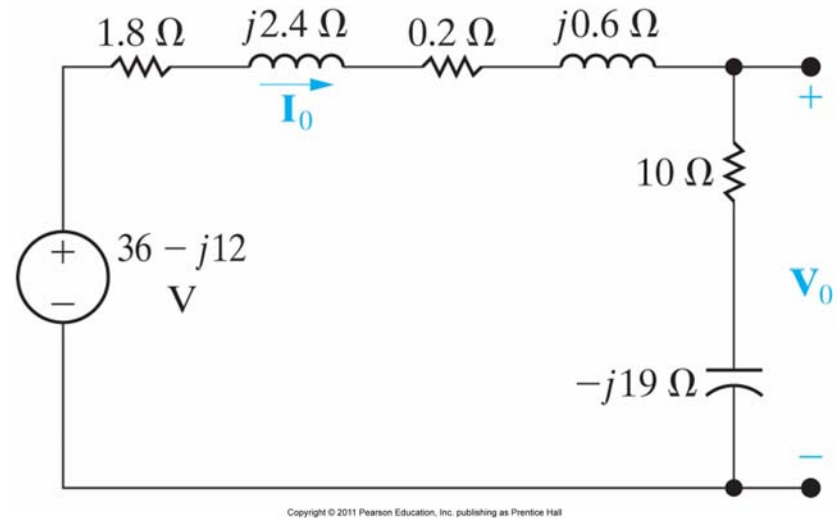
**Figure 9.27** The circuit for Example 9.9.



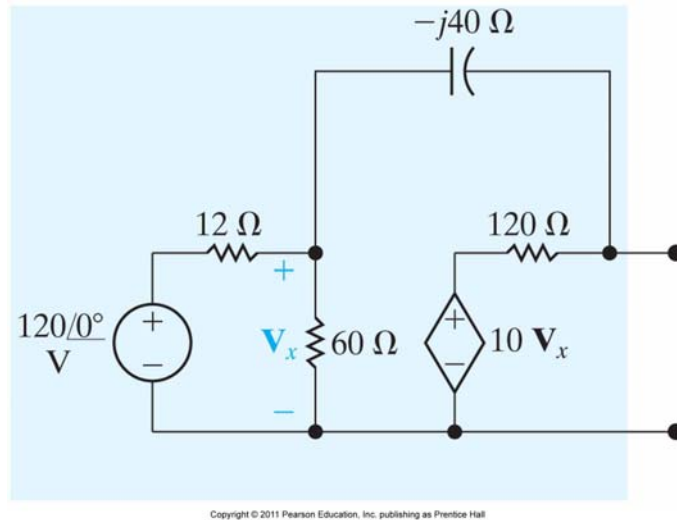
**Figure 9.28** The first step in reducing the circuit shown in Fig. 9.27



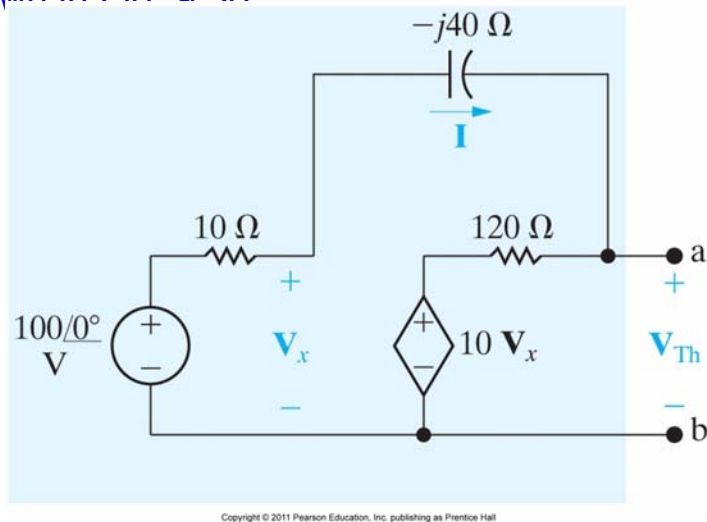
**Figure 9.29** The second step in reducing the circuit shown in Fig. 9.27.



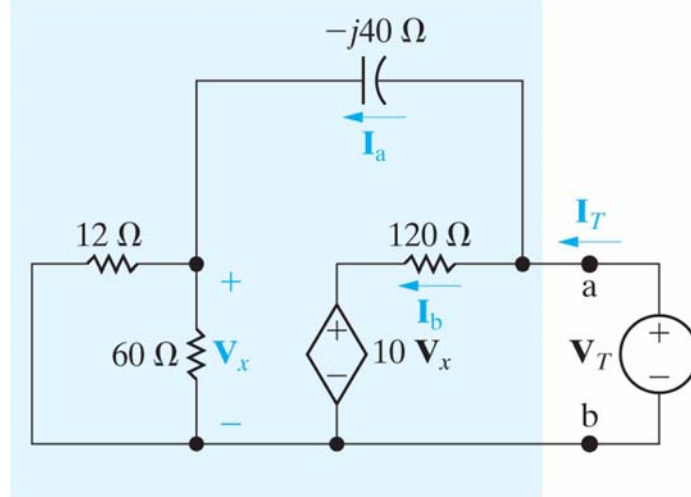
**Figure 9.30** The circuit for Example 9.10.



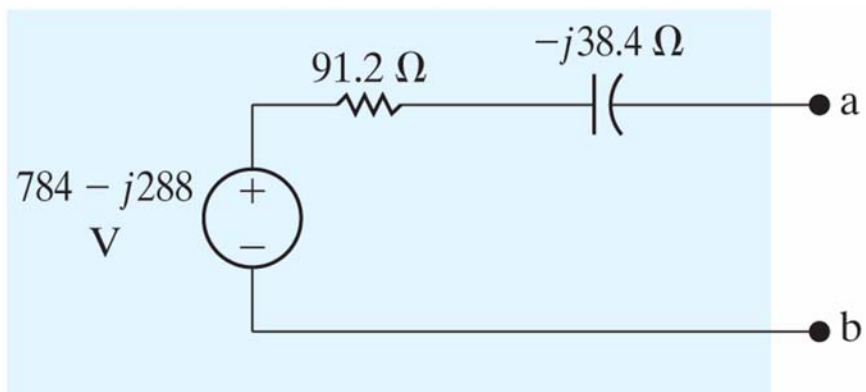
**Figure 9.31** A simplified version of the circuit shown in Fig. 9.30.



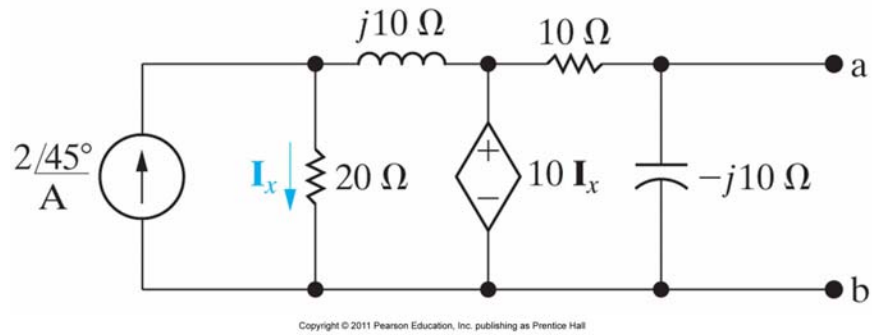
**Figure 9.32** A circuit for calculating the Thévenin equivalent impedance.



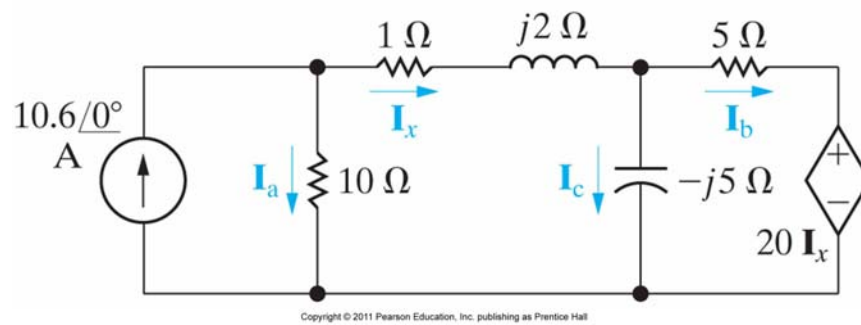
**Figure 9.33** The Thévenin equivalent for the circuit shown in Fig. 9.30.



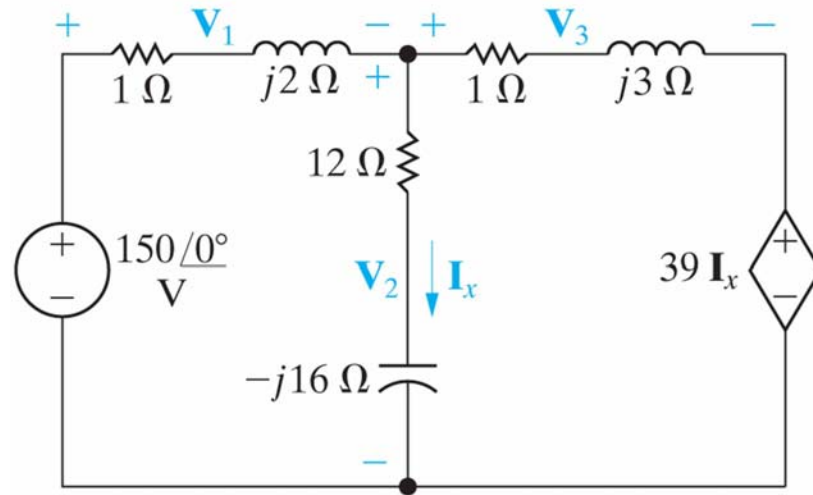
**Figure 9.34** The circuit for Example 9.11.



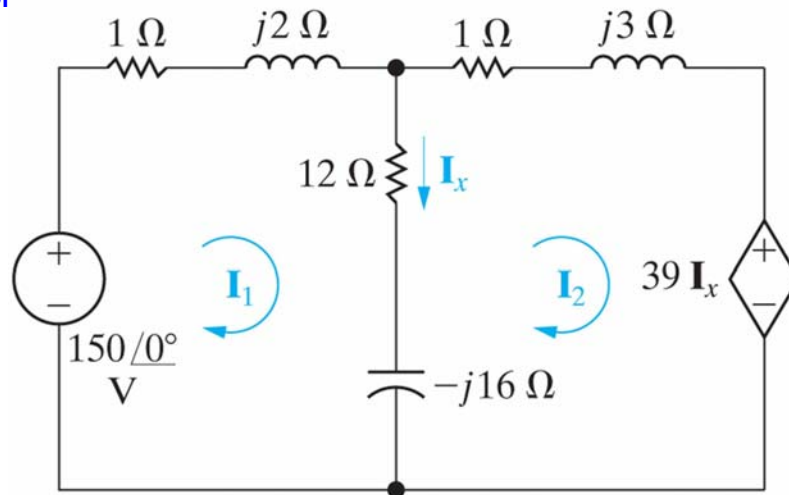
**Figure 9.35** The circuit shown in Fig. 9.34, with the node voltages defined.

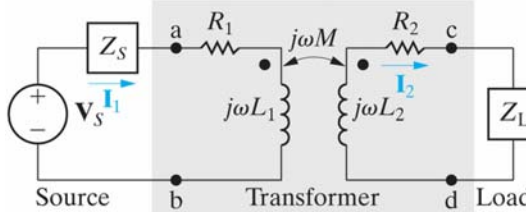


**Figure 9.36** The circuit for Example 9.12.



**Figure 9.37** Mesh currents used to solve the circuit shown in Fig. 9.36





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$$V_s = I_1(Z_s + R_1 + j\omega L_1) - I_2 j\omega M$$

$$0 = -j\omega M I_1 + I_2(R_2 + j\omega L_2 + Z_L)$$

$$j\omega M I_1 = I_2(R_2 + j\omega L_2 + Z_L)$$

$$I_2 = \frac{j\omega M I_1}{(R_2 + j\omega L_2 + Z_L)}$$

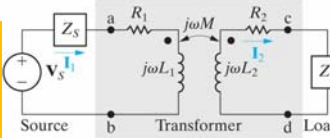
$$Z_{11} = Z_s + R_1 + j\omega L_1$$

$$Z_{22} = Z_L + R_2 + j\omega L_2$$

$$I_1 = \frac{Z_{22}}{Z_{11}Z_{22} + \omega^2 M^2} V_s$$

$$\frac{V_2}{I_1} = Z_{total} = Z_{11} + \frac{\omega^2 M^2}{Z_{22}}$$

Impedance in the primary loop      Reflected impedance



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$$Z_{reflected} = \frac{\omega^2 M^2}{Z_{22}}$$

$$Z_{reflected} = \frac{\omega^2 M^2}{R_2 + j\omega L_2 + Z_L}$$

$$Z_{reflected} = \frac{\omega^2 M^2}{R_2 + j\omega L_2 + R_L + j\omega X_L}$$

$$Z_{reflected} = \frac{\omega^2 M^2}{(R_2 + R_L) + j\omega(L_2 + X_L)}$$

$$Z_{reflected} = \frac{\omega^2 M^2}{|Z_{22}|^2} [(R_2 + R_L) - j\omega(L_2 + X_L)]$$

The complex conjugate of the self impedance of the secondary circuit scaled by a factor