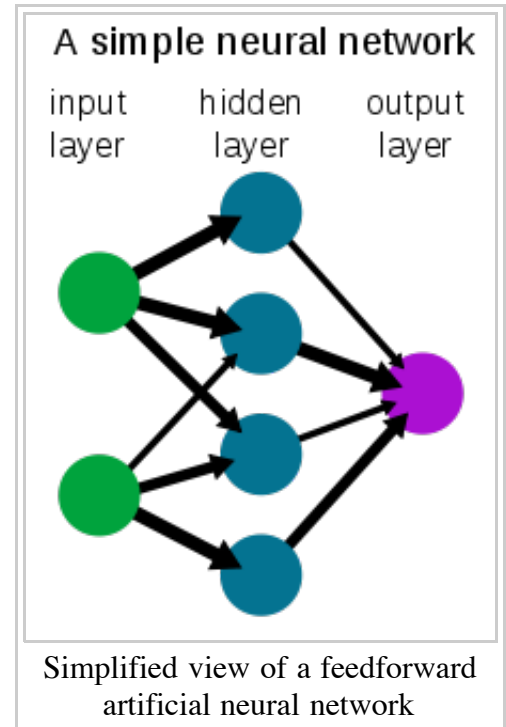


Neural network

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The term **neural network** was traditionally used to refer to a network or circuit of biological neurons.^[1] The modern usage of the term often refers to artificial neural networks, which are composed of artificial neurons or nodes. Thus the term has two distinct usages:

1. Biological neural networks are made up of real biological neurons that are connected or functionally related in the peripheral nervous system or the central nervous system. In the field of neuroscience, they are often identified as groups of neurons that perform a specific physiological function in laboratory analysis.
2. Artificial neural networks are made up of interconnecting artificial neurons (programming constructs that mimic the properties of biological neurons). Artificial neural networks may either be used to gain an understanding of biological neural networks, or for solving artificial intelligence problems without necessarily creating a model of a real biological system. The real, biological nervous system is highly complex and includes some features that may seem superfluous based on an understanding of artificial networks.



This article focuses on the relationship between the two concepts; for detailed coverage of the two different concepts refer to the separate articles: Biological neural network and Artificial neural network.

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Overview

In general, a biological neural network is composed of a group or groups of chemically connected or functionally associated neurons. A single neuron may be connected to many other neurons and the total number of neurons and connections in a network may be extensive. Connections, called synapses, are usually formed from axons to dendrites, though dendrodendritic microcircuits^[2] and other connections are possible. Apart from the electrical signaling, there are other forms of signaling that arise from neurotransmitter diffusion, which have an effect on electrical signaling. As such, neural networks are extremely complex.

Artificial intelligence and cognitive modeling try to simulate some properties of neural networks. While similar in their techniques, the former has the aim of solving particular tasks, while the latter aims to build mathematical models of biological neural systems.

In the artificial intelligence field, artificial neural networks have been applied successfully to speech recognition, image analysis and adaptive control, in order to construct software agents (in computer and video games) or autonomous robots. Most of the currently employed artificial neural networks for artificial intelligence are based on statistical estimation, optimization and control theory.

The cognitive modelling field involves the physical or mathematical modeling of the behaviour of neural systems; ranging from the individual neural level (e.g. modelling the spike response curves of neurons to a stimulus), through the neural cluster level (e.g. modelling the release and effects of dopamine in the basal ganglia) to the complete organism (e.g. behavioural modelling of the organism's response to stimuli). Artificial intelligence, cognitive modelling, and neural networks are information processing paradigms inspired by the way biological neural systems process data.

History of the neural network analogy

Main article: Connectionism

In the brain, spontaneous order arises out of decentralized networks of simple units (neurons). In the late 1940s Donald Hebb made one of the first hypotheses of learning with a mechanism of neural plasticity called Hebbian learning. Hebbian learning is considered to be a 'typical' unsupervised learning rule and its later variants were early models for long term potentiation. These ideas started being applied to computational models in 1948 with Turing's B-type machines and the perceptron.

The perceptron is essentially a linear classifier for classifying data $x \in \mathbb{R}^n$ specified by parameters $w \in \mathbb{R}^n$, $b \in \mathbb{R}$ and an output function $f = w \cdot x + b$. Its parameters are adapted with an ad-hoc rule similar to stochastic steepest gradient descent. Because the inner product is a linear operator in the input space, the perceptron can only perfectly classify a set of data for which different classes are linearly separable in the input space, while it often fails completely for non-separable data. While the development of the algorithm initially generated some enthusiasm, partly because of its apparent relation to biological mechanisms, the later discovery of this inadequacy caused such models to be abandoned until the introduction of non-linear models into the field.

The **cognitron** (1975) designed by Kuniyiko Fukushima^[3] was an early multilayered neural network with a training algorithm. The actual structure of the network and the methods used to set the interconnection weights change from one neural strategy to another, each with its advantages and disadvantages. Networks can propagate information in one direction only, or they can bounce back and forth until self-activation at a node occurs and the network settles on a final state. The ability for bi-directional flow of inputs between neurons/nodes was produced with the Hopfield's network (1982), and specialization of these node layers for specific purposes was introduced through the first hybrid network.

The parallel distributed processing of the mid-1980s became popular under the name connectionism.

The rediscovery of the backpropagation algorithm was probably the main reason behind the repopularisation of neural networks after the publication of "Learning Internal Representations by Error Propagation" in 1986 (Though backpropagation itself dates from 1969). The original network utilized multiple layers of weight-sum units of the type $f = g(w'x + b)$, where g was a sigmoid function or logistic function such as used in logistic regression. Training was done by a form of stochastic Gradient descent. The employment of the chain rule of differentiation in deriving the appropriate parameter updates results in an algorithm that seems to 'backpropagate errors', hence the nomenclature. However it is essentially a form of gradient descent. Determining the optimal parameters in a model of this type is not trivial, and steepest gradient descent methods cannot be relied upon to give the solution without a good starting point. In recent times, networks with the same architecture as the backpropagation network are referred to as Multi-Layer Perceptrons. This name does not impose any limitations on the type of algorithm used for learning.

The backpropagation network generated much enthusiasm at the time and there was much controversy about whether such learning could be implemented in the brain or not, partly because a mechanism for reverse signaling was not obvious at the time, but most importantly because there was no plausible source for the 'teaching' or 'target' signal.

The brain, neural networks and computers

Neural networks, as used in artificial intelligence, have traditionally been viewed as simplified models of neural processing in the brain, even though the relation between this model and brain biological architecture is debated, as little is known about how the brain actually works.^[*citation needed*]

A subject of current research in theoretical neuroscience is the question surrounding the degree of complexity and the properties that individual neural elements should have to reproduce something resembling animal intelligence.

Historically, computers evolved from the von Neumann architecture, which is based on sequential processing and execution of explicit instructions. On the other hand, the origins of neural networks are based on efforts to model information processing in biological systems, which may rely largely on parallel processing as well as implicit instructions based on recognition of patterns of 'sensory' input from external sources. In other words, at its very heart a neural network is a complex statistical processor (as opposed to being tasked to sequentially process and execute).

Neural coding is concerned with how sensory and other information is represented in the brain by neurons. The

main goal of studying neural coding is to characterize the relationship between the stimulus and the individual or ensemble neuronal responses and the relationship among electrical activity of the neurons in the ensemble.^[4] It is thought that neurons can encode both digital and analog information.^[5]

Neural networks and artificial intelligence

Main article: Artificial neural network

A *neural network* (NN), in the case of artificial neurons called *artificial neural network* (ANN) or *simulated neural network* (SNN), is an interconnected group of natural or artificial neurons that uses a mathematical or computational model for information processing based on a connectionistic approach to computation. In most cases an ANN is an adaptive system that changes its structure based on external or internal information that flows through the network.

In more practical terms neural networks are non-linear statistical data modeling or decision making tools. They can be used to model complex relationships between inputs and outputs or to find patterns in data.

However, the paradigm of neural networks - i.e., *implicit*, not *explicit*, learning is stressed - seems more to correspond to some kind of *natural intelligence* than to the traditional *Artificial Intelligence*, which would stress, instead, rule-based learning.

Background

An artificial neural network involves a network of simple processing elements (artificial neurons) which can exhibit complex global behavior, determined by the connections between the processing elements and element parameters. Artificial neurons were first proposed in 1943 by Warren McCulloch, a neurophysiologist, and Walter Pitts, an MIT logician.^[2] (http://palisade.com/neuraltools/neural_networks.asp) One classical type of artificial neural network is the recurrent Hopfield net.

In a neural network model simple nodes, which can be called variously "neurons", "neurodes", "Processing Elements" (PE) or "units", are connected together to form a network of nodes — hence the term "neural network". While a neural network does not have to be adaptive *per se*, its practical use comes with algorithms designed to alter the strength (weights) of the connections in the network to produce a desired signal flow.

In modern software implementations of artificial neural networks the approach inspired by biology has more or less been abandoned for a more practical approach based on statistics and signal processing. In some of these systems, neural networks, or parts of neural networks (such as artificial neurons), are used as components in larger systems that combine both adaptive and non-adaptive elements.

The concept of a neural network appears to have first been proposed by Alan Turing in his 1948 paper "Intelligent Machinery".

Applications of natural and of artificial neural networks

The utility of artificial neural network models lies in the fact that they can be used to infer a function from

observations and also to use it. This is particularly useful in applications where the complexity of the data or task makes the design of such a function by hand impractical.

Real life applications

The tasks to which artificial neural networks are applied tend to fall within the following broad categories:

- Function approximation, or regression analysis, including time series prediction and modeling.
- Classification, including pattern and sequence recognition, novelty detection and sequential decision making.
- Data processing, including filtering, clustering, blind signal separation and compression.

Application areas of ANNs include system identification and control (vehicle control, process control), game-playing and decision making (backgammon, chess, racing), pattern recognition (radar systems, face identification, object recognition, etc.), sequence recognition (gesture, speech, handwritten text recognition), medical diagnosis, financial applications, data mining (or knowledge discovery in databases, "KDD"), visualization and e-mail spam filtering.

Neural networks and neuroscience

Theoretical and computational neuroscience is the field concerned with the theoretical analysis and computational modeling of biological neural systems. Since neural systems are intimately related to cognitive processes and behaviour, the field is closely related to cognitive and behavioural modeling.

The aim of the field is to create models of biological neural systems in order to understand how biological systems work. To gain this understanding, neuroscientists strive to make a link between observed biological processes (data), biologically plausible mechanisms for neural processing and learning (biological neural network models) and theory (statistical learning theory and information theory).

Types of models

Many models are used in the field, each defined at a different level of abstraction and trying to model different aspects of neural systems. They range from models of the short-term behaviour of individual neurons, through models of how the dynamics of neural circuitry arise from interactions between individual neurons, to models of how behaviour can arise from abstract neural modules that represent complete subsystems. These include models of the long-term and short-term plasticity of neural systems and its relation to learning and memory, from the individual neuron to the system level.

Current research

While initially research had been concerned mostly with the electrical characteristics of neurons, a particularly important part of the investigation in recent years has been the exploration of the role of neuromodulators such as dopamine, acetylcholine, and serotonin on behaviour and learning.

Biophysical models, such as BCM theory, have been important in understanding mechanisms for synaptic

plasticity, and have had applications in both computer science and neuroscience. Research is ongoing in understanding the computational algorithms used in the brain, with some recent biological evidence for radial basis networks and neural backpropagation as mechanisms for processing data.

Computational devices have been created in CMOS for both biophysical simulation and neuromorphic computing. More recent efforts show promise for creating nanodevices^[6] for very large scale principal components analyses and convolution. If successful, these efforts could usher in a new era of neural computing^[7] that is a step beyond digital computing, because it depends on learning rather than programming and because it is fundamentally analog rather than digital even though the first instantiations may in fact be with CMOS digital devices.

Criticism

A common criticism of neural networks, particularly in robotics, is that they require a large diversity of training for real-world operation. Dean Pomerleau, in his research presented in the paper "Knowledge-based Training of Artificial Neural Networks for Autonomous Robot Driving," uses a neural network to train a robotic vehicle to drive on multiple types of roads (single lane, multi-lane, dirt, etc.). A large amount of his research is devoted to (1) extrapolating multiple training scenarios from a single training experience, and (2) preserving past training diversity so that the system does not become overtrained (if, for example, it is presented with a series of right turns – it should not learn to always turn right). These issues are common in neural networks that must decide from amongst a wide variety of responses.

A. K. Dewdney, a former *Scientific American* columnist, wrote in 1997, "Although neural nets do solve a few toy problems, their powers of computation are so limited that I am surprised anyone takes them seriously as a general problem-solving tool." (Dewdney, p. 82)

Arguments for Dewdney's position are that to implement large and effective software neural networks, much processing and storage resources need to be committed. While the brain has hardware tailored to the task of processing signals through a graph of neurons, simulating even a most simplified form on Von Neumann technology may compel a NN designer to fill many millions of database rows for its connections - which can lead to abusive RAM and HD necessities. Furthermore, the designer of NN systems will often need to simulate the transmission of signals through many of these connections and their associated neurons - which must often be matched with incredible amounts of CPU processing power and time. While neural networks often yield *effective* programs, they too often do so at the cost of time and money *efficiency*.

Arguments against Dewdney's position are that neural nets have been successfully used to solve many complex and diverse tasks, ranging from autonomously flying aircraft [3] (<http://www.nasa.gov/centers/dryden/news/NewsReleases/2003/03-49.html>) to detecting credit card fraud [4] (<http://www.visa.ca/en/about/visabenefits/innovation.cfm>) .

Technology writer Roger Bridgman commented on Dewdney's statements about neural nets:

Neural networks, for instance, are in the dock not only because they have been hyped to high heaven, (what hasn't?) but also because you could create a successful net without understanding how it worked: the bunch of numbers that captures its behaviour would in all probability be "an

opaque, unreadable table...valueless as a scientific resource". In spite of his emphatic declaration that science is not technology, Dewdney seems here to pillory neural nets as bad science when most of those devising them are just trying to be good engineers. An unreadable table that a useful machine could read would still be well worth having.^[8]

Some other criticisms came from believers of hybrid models (combining neural networks and symbolic approaches). They advocate the intermix of these two approaches and believe that hybrid models can better capture the mechanisms of the human mind (Sun and Bookman 1990).

See also

- ADALINE
- 20Q is a neural network implementation of the 20 questions game
- Artificial neural network
- Biological cybernetics
- Biologically inspired computing
- Cerebellar Model Articulation Controller
- Cognitive architecture
- Cognitive science
- Cultured neuronal networks
- Digital morphogenesis
- Group method of data handling
- In Situ Adaptive Tabulation
- Memristor
- Neural network software
- Neuroscience
- Parallel distributed processing
- Predictive analytics
- Radial basis function network
- Recurrent neural networks
- Simulated reality
- Support vector machine
- Tensor product network
- Time delay neural network
- Parallel Constraint Satisfaction Processes

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2. ^ Arbib, p.666
3. ^ Fukushima, Kunihiko (1975). "Cognitron: A self-organizing multilayered neural network". *Biological Cybernetics* **20** (3-4): 121–136. doi:10.1007/BF00342633 (<http://dx.doi.org/10.1007%2FBF00342633>) . PMID 1203338 (<http://www.ncbi.nlm.nih.gov/pubmed/1203338>) .
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External links

- LearnArtificialNeuralNetworks (<http://www.learnartificialneuralnetworks.com/robotcontrol.html>) - Robot control and neural networks
- Review of Neural Networks in Materials Science (<http://www.msm.cam.ac.uk/phase-trans/abstracts/neural.review.html>)
- Artificial Neural Networks Tutorial in three languages (Univ. Politécnica de Madrid) (<http://www.gc.ssr.upm.es/inves/neural/ann1/anntutorial.html>)
- Introduction to Neural Networks and Knowledge Modeling (<http://www.makhfi.com/tutorial/introduction.htm>)
- Another introduction to ANN (http://www.doc.ic.ac.uk/~nd/surprise_96/journal/vol4/cs11/report.html)
- Next Generation of Neural Networks (<http://youtube.com/watch?v=AyzOUbkUf3M>) - Google Tech Talks
- Performance of Neural Networks (<http://www.msm.cam.ac.uk/phase-trans/2009/performance.html>)
- Neural Networks and Information (http://www.msm.cam.ac.uk/phase-trans/2009/review_Bhadeshia_SADM.pdf)
- PMML Representation (<http://www.dmg.org/v4-0/NeuralNetwork.html>) - Standard way to represent neural networks

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