LE/EECS 3213 E Communication Networks Fall 2014 Quiz #4, Thurs. Nov. 27, 2014

Name:

**1.** (5 points)

1.) [1] In (only) 1 word: What important function in the receiver does a Manchester code assist?

Synchronization

2.) [1] What is the drawback of a Manchester code? increcsed bandwidth

## 3.) [1] In digital receivers when adjacent data symbols start to interfere with each other we call that $\dots$ $T \leq T$

4.) [1] What is the maximum number of symbols/s/Hz that I can send in a binary bandpass scheme.

5.) [1] What is the maximum number of symbols/s/Hz that I can send in a binary passband scheme using a single carrier.



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2. (3 points) You are to send 10111000 using a differential line code. What is the sequence of bits that comes out of your differential line coder?



**3.** (3 points) Sketch a 16-QAM constellation.



4. (4 points) A 256 point constellation is to achieve a data rate of 15-Mbps. What is the minimum channel bandwidth needed to support this requirement?

$$M = 256$$
 # of bits per symbol =  $m = log_2(M) = 86$ ; ts  
 $\frac{15 \text{ Mbps}}{8 \text{ bits}} = 1.875 \text{ MHz} \leftarrow \text{bandpass channel bw meedled}$ 

 $c = 3 \times 10^8$  m/s (in free space),  $c = 2 \times 10^8$  m/s (in media), 1 nm =  $10^{-9}$  m, 1 ms =  $10^{-3}$  s, 1 GHz =  $10^9$  Hz

$$\begin{split} \log_{x} y &= \frac{\log_{a} y}{\log_{a} x} \\ C &= W_{c} \log_{2}(1 + \text{SNR}) \\ y &= \int_{a}^{b} x dx = \frac{x^{2}}{2} \Big|_{a}^{b} = (b^{2} - a^{2})/2, y = \int_{a}^{b} x^{2} dx = \frac{x^{3}}{3} \Big|_{a}^{b} = (b^{3} - a^{3})/3 \\ y(t) &= a_{0} + \sum_{k=1}^{\infty} a_{k} \cos(2\pi f_{0} \cdot k \cdot t) + \sum_{k=1}^{\infty} b_{k} \sin(2\pi f_{0} \cdot k \cdot t) \\ f_{0} &= \frac{1}{T}, a_{0} = \frac{1}{T} \int_{0}^{T} y(t) dt, a_{k} = \frac{2}{T} \int_{0}^{T} y(t) \cdot \cos(2\pi f_{0} \cdot k \cdot t) dt, b_{k} = \frac{2}{T} \int_{0}^{T} y(t) \cdot \sin(2\pi f_{0} \cdot k \cdot t) dt \\ \text{SNR [dB] = 10 \log(\text{SNR}), \text{SNR [dB] = 6m - 10 \log(3\sigma_{x}^{2}/V^{2}), \sigma_{q}^{2} = \Delta^{2}/12 \\ \mathcal{F}\{\text{rect}(t/T)\} = T \operatorname{sin}(fT) = T \sin(\pi fT)/\pi fT \\ \mathcal{F}\{\operatorname{sinc}(t/T)\} = T \operatorname{rect}(fT) \\ B &= v \Delta \lambda/\lambda^{2} \end{split}$$